HART® field temperature transmitter Models TIF50, TIF52

for further approvals see page 10

Applications

- Plant construction
- Process engineering
- General industrial applications
- Oil and gas

Special features

- Setting of units and measuring range possible on site (only model TIF52)
- Different hazardous area approvals
- The following settings are possible via external software:
  - Dual sensor, redundant measurement possible
  - Customer-specific characteristic curves programmable

Field temperature transmitters models TIF50, TIF52

Description

The TIF series field temperature transmitters, consisting of a rugged field case, model T32 temperature transmitter and a model DIH display, have been designed for general use in process engineering.

They offer high accuracy, galvanic isolation and excellent protection against electromagnetic influences (EMI). Via HART® protocol, the TIFxx is configurable (interoperable) with a variety of open configuration tools.

In addition to the different sensor types, e.g. sensors in accordance with DIN EN 60751, JIS C1606, DIN 43760, IEC 60584 or DIN 43710, customer-specific sensor characteristics can also be defined, through the input of value pairs (user-defined linearisation). Through the configuration of a sensor with redundancy (dual sensor), on a sensor failure it will automatically change over to the working sensor.

Furthermore, there is the possibility to activate sensor drift detection. With this, an error signalling occurs when the magnitude of the temperature difference between sensor 1 and sensor 2 exceeds a user-selectable value.

The field temperature transmitter also has additional sophisticated supervisory functionality such as monitoring of the sensor lead resistance and sensor-break detection in accordance with NAMUR NE89 as well as monitoring of the measuring range. Moreover, these transmitters have comprehensive cyclic self-monitoring functionality.

Via the display it is possible to show range alarms as well as MIN and MAX values.

The field temperature transmitter is available in various field case variants. Stainless steel and aluminium can be specified.
It can be mounted directly on a wall. A pipe mounting kit is also available for fitting to pipes with a diameter of 1 ... 2".

The field temperature transmitters are delivered with a basic configuration or configured according to customer specifications.

Data sheets showing similar products:
Digital temperature transmitter, head- and rail-mounted version; models T32.1S, T32.3S; see data sheet TE 32.04
Field indicator for current loops with HART® communication; models DIH50, DIH52; see data sheet AC 80.10

Specifications

Field temperature transmitter input							
Sensor type		**Max. configurable measuring range** [1]	**Standard**	**α values**	**Minimum measuring span** [14]	**Typical measuring deviation** [2]	**Temperature coefficient per °C typical** [3]
Resistance sensor	**Pt100**	-200 ... +850 °C	**IEC 60751**:2008	**α = 0.00385**	10 K or 3.8 Ω (greater value applies)	≤ ±0.12 °C [5]	≤ ±0.0094 °C [6] [7]
	Pt(x) [4] 10 ... 1000	-200 ... +850 °C	IEC 60751:2008	α = 0.00385		≤ ±0.12 °C [5]	≤ ±0.0094 °C [6] [7]
	JPt100	-200 ... +500 °C	JIS C1606: 1989	α = 0.003916		≤ ±0.12 °C [5]	≤ ±0.0094 °C [6] [7]
	Ni100	-60 ... +250 °C	DIN 43760: 1987	α = 0.00618		≤ ±0.12 °C [5]	≤ ±0.0094 °C [6] [7]
	Resistance sensor	*0 ... 8,370 Ω*			*4 Ω*	*≤ ±1.68 Ω* [8]	*≤ ±0.1584 Ω* [8]
	Potentiometer [9]	*0 ... 100 %*			*10 %*	*≤ 0.50 %* [10]	*≤ ±0.0100 %* [10]
Measuring current during measurement		Max. 0.3 mA (Pt100)					
Connection methods		1 sensor 2-/4-/3-wire or 2 sensors 2-wire (for further information, please refer to “Designation of connection terminals”)					
Max. lead resistance		50 Ω each wire, 3-/4-wire					
Thermo-couple	Type J (Fe-CuNi)	-210 ... +1,200 °C	IEC 60584-1: 1995		50 K or 2 mV (greater value applies)	≤ ±0.91 °C [11]	≤ ±0.0217 °C [7] [11]
	Type K (NiCr-Ni)	-270 ... +1,300 °C	IEC 60584-1: 1995			≤ ±0.98 °C [11]	≤ ±0.0238 °C [7] [11]
	Type L (Fe-CuNi)	-200 ... +900 °C	DIN 43760: 1987			≤ ±0.91 °C [11]	≤ ±0.0203 °C [7] [11]
	Type E (NiCr-Cu)	-270 ... +1,000 °C	IEC 60584-1: 1995			≤ ±0.91 °C [11]	≤ ±0.0224 °C [7] [11]
	Type N (NiCrSi-NiSi)	-270 ... +1,300 °C	IEC 60584-1: 1995			≤ ±1.02 °C [11]	≤ ±0.0238 °C [7] [11]
	Type T (Cu-CuNi)	-270 ... +400 °C	IEC 60584-1: 1995			≤ ±0.92 °C [11]	≤ ±0.0191 °C [7] [11]
	Type U (Cu-CuNi)	-200 ... +600 °C	DIN 43710: 1985			≤ ±0.92 °C [11]	≤ ±0.0191 °C [7] [11]
	Type R (PtRh-Pt)	-50 ... +1,768 °C	IEC 60584-1: 1995		150 K	≤ ±1.66 °C [11]	≤ ±0.0338 °C [7] [11]
	Type S (PtRh-Pt)	-50 ... +1,768 °C	IEC 60584-1: 1995		150 K	≤ ±1.66 °C [11]	≤ ±0.0338 °C [7] [11]
	Type B (PtRh-Pt)	0 ... +1,820 °C [15]	IEC 60584-1: 1995		200 K	≤ ±1.73 °C [11]	≤ ±0.0500 °C [7] [12]
	mV sensor	*-500 ... +1,800 mV*			*4 mV*	*≤ ±0.33 mV* [13]	*≤ ±0.0311 mV* [7] [13]
Connection methods		1 sensor or 2 sensors (for further information, please refer to “Designation of connection terminals”)					
Max. lead resistance		5 kΩ each wire					
Cold junction compensation, configurable		internal compensation or external with Pt100, with thermostat or off					

1) Other units e.g. °F and K possible
2) Measuring deviations (input + output) at ambient temperature 23 °C ±3 K, without influence of lead resistances; for example calculations see page 5
3) Temperature coefficients (input + output) per °C
4) x configurable between 10 … 1,000
5) Based on 3-wire Pt100, Ni100, 150 °C MV
6) Based on 150 °C MV
7) In the ambient temperature range -40 … +85 °C
8) Based on a sensor with max. 5 kΩ
9) Rtotal: 10 ... 100 kΩ
10) Based on a potentiometer value of 50 %
11) Based on 400 °C MV with cold junction compensation error
12) Based on 1.000 °C MV with cold junction compensation error
13) Based on measuring range 0 ... 1 V, 400 mV MV
14) The transmitter can be configured below these limits, but this is not recommended due to loss of accuracy.
15) Specifications valid only for measuring range between 450 ... 1,820 °C

MV = measured value (temperature measured values in °C)

Note:
The transmitter can be configured below these limits, but this is not recommended due to loss of accuracy.

The selection of the sensor is only possible via the HART® software (e.g. WIKA_T32) or the HART® communicator (e.g. FC475, MFC4150).
WIKA configuration software WIKA_T32: Free download from www.wika.com

User linearisation

Via software, customer-specific sensor characteristics can be stored in the transmitter, so that further sensor types can be used. Number of data points: Minimum 2; maximum 30

Monitoring functionality with 2 sensors connected (dual sensor)

Redundancy

In the case of a sensor error (sensor break, lead resistance too high or outside the measuring range of the sensor) of one of the two sensors, the process value will be only based on the error-free sensor. Once the error is rectified, the process value will again be based on the two sensors or on sensor 1.

Ageing control (sensor-drift monitoring)

An error signal on the output is activated if the value of the temperature difference between sensor 1 and sensor 2 is higher than a set value, which can be selected by the user. This monitoring only generates a signal if two valid sensor values can be determined and the temperature difference is higher than the selected limit value.
(Cannot be selected for the “Difference” sensor function, since the output signal already indicates the difference value).

Sensor functionality when 2 sensors have been connected (dual sensor)

Sensor 1, sensor 2 redundant

The 4 … 20 mA output signal delivers the process value of sensor 1. If sensor 1 fails, the process value of sensor 2 is output (sensor 2 is redundant).

Mean value

The 4 ... 20 mA output signal delivers the mean value of the two values from sensor 1 and sensor 2. If one sensor fails, the process value of the error-free sensor is output.

Minimum value

The 4 ... 20 mA output signal delivers the lower of the two values from sensor 1 and sensor 2. If one sensor fails, the process value of the error-free sensor is output.

Maximum value

The 4 ... 20 mA output signal delivers the higher of the two values from sensor 1 and sensor 2. If one sensor fails, the process value of the error-free sensor is output.

Difference

The 4 ... 20 mA output signal delivers the difference between sensor 1 and sensor 2. If one sensor fails, an error signalling will be activated.

Display, operating unit	Model TIF50	Model TIF52
Display principle	LCD, rotatable in 10° steps	
Measured value of display	7-segment LCD, 5-digit, character size 9 mm	
Bar graph	20-segment LCD	
Info line	14-segment LCD, 6-digit, character size 5.5 mm	
Status indicators	♥ : HART® mode (signalling of HART® parameter adoption) : Unit lock ⚠ : Warnings or error messages	
Indication range	-9999 ... 99999	
Measuring rate	approx. 4/s	
Accuracy	±0.1 % of measuring span	±0.05 % of measuring span
Temperature coefficient	±0.1 % of measuring span / 10 K	
HART® functionality		
■ Access control	-	Secondary master
■ Automatically set parameters		
■ Available commands	-	Unit, measuring range start/end, format, zero point, span, damping, polling address
■ Identified commands	Generic mode: 1, 15, 35, 44	Generic mode: 0, 1, 6, 15, 34, 35, 36, 37, 44
■ Multidrop	Not supported	Measured values are automatically taken from the HART® digital data and displayed

Rise time, damping, measuring rate	
Rise time t_{90}	Approx. 0.8 s
Damping, configurable	**Off**; configurable between 1 s and 60 s
Switch-on time (time to get the first measured value)	Max. 15 s
Measuring rate [1]	Measured value update approx. 3/s

Bold: Basic configuration
1) Valid only for RTD/single thermocouple sensor

Analogue output, output limits, signalling, insulation resistance		
Analogue output, configurable	**Linear to temperature per IEC 60751** / JIS C1606 / DIN 43760 (for resistance sensors) or linear to temperature per IEC 584 / DIN 43710 (for thermocouples) 4 ... 20 mA or 20 ... 4 mA, 2-wire	
Output limits, configurable **per NAMUR NE43** customer-specifically adjustable	Lower limit **3.8 mA** 3.6 ... 4.0 mA	upper limit **20.5 mA** 20.0 ... 21.5 mA
Current value for signalling, configurable **per NAMUR NE43** Substitute value	**Downscale** **< 3.6 mA (3.5 mA)** 3.5 ... 12.0 mA	upscale > 21.0 mA (21.5 mA) 12.0 ... 23.0 mA
In simulation mode, independent from input signal, simulation value configurable from 3.5 ... 23.0 mA		
Load R_A (without HART®)	$R_A \leq (U_B - 13.5\ V) / 0.023\ A$ with R_A in Ω and U_B in V	
Load R_A (with HART®)	$R_A \leq (U_B - 14.5\ V) / 0.023\ A$ with R_A in Ω and U_B in V	
Insulation voltage (input to analogue output)	AC 1,200 V (50 Hz / 60 Hz); 1 s	
Insulation specification to DIN EN 60664-1:2003	Overvoltage category III	

Bold: Basic configuration

Explosion protection, power supply					
Model	**Approvals**	**Permissible ambient/storage temperature (in accordance with the relevant temperature classes)**	**Safety-related maximum values**		**Power supply U_B (DC)**
			Sensor (Connections 1 - 4)	**Current loop (Connections ±)**	
TIF50-S, **TIF52-S**	without	{-50} -40 ... +85 °C	-	-	14.5 ... 42 V
TIF50-F, **TIF52-F**	Flameproof enclosure BVS 10 ATEX E 158 IECEx BVS 10.0103 II 2G Ex db IIC T4/T5/T6 Gb Ex db IIC T4/T5/T6 Gb	-40 ... +85 °C at T4 -40 ... +75 °C at T5 -40 ... +60 °C at T6	-	U_M = 30 V P_M = 2 W	14.5 ... 30 V
TIF50-F, **TIF52-F**	Flameproof enclosure TC RU C-DE.BH02.B.00466/20 1 Ex d IIC T6 ... T4	-60 [2] / -40 ... +85 °C at T4 -60 [2] / -40 ... +75 °C at T5 -60 [2] / -40 ... +60 °C at T6	-	U_M = 30 V P_M = 2 W	14.5 ... 30 V
TIF50-I, **TIF52-I**	Intrinsically safe equipment [1] BVS 16 ATEX E 112 X IECEx BVS 16.0075X		see installation drawing in the operating instructions at www.wika.com	see installation drawing in the operating instructions at www.wika.com	14.5 ... 29 V
	II (1)2G Ex ia [ia Ga] IIC T4/T5/T6 Gb II 2G Ex ia IIC T4/T5/T6 Gb	-40 ... +85 °C at T4 -40 ... +70 °C at T5 -40 ... +55 °C at T6			
	II (1)2D Ex ia [ia Da] IIIC T135 °C Db II 2D Ex ia IIIC T135 °C Db	-40 ... +40 °C (P_i = 680 mW) -40 ... +70 °C (P_i = 650 mW)			
TIF50-I, **TIF52-I**	Intrinsically safe equipment [1] TC RU C-DE.АЯ45.B.00918		see installation drawing in the operating instructions at www.wika.com	see installation drawing in the operating instructions at www.wika.com	14.5 ... 29 V
	0 Ex ia IIC T4/T5/T6 1 Ex ib [ia] IIC T4/T5/T6	-60 [2] / -40 ... +85 °C at T4 -60 [2] / -40 ... +70 °C at T5 -60 [2] / -40 ... +55 °C at T6			
	DIP A20 Ta 120 °C DIP A21 Ta 120 °C	-60 [2] / -40 ... +40 °C (P_i = 680 mW) -60 [2] / -40 ... +70 °C (P_i = 650 mW)			

1) The installation conditions for the transmitters and displays must be considered for the final application.
2) Special version on request (only available with specific approvals)

Measuring deviation, temperature coefficient, long-term stability

Effect of load	Not measurable
Power supply effect	Not measurable
Warm-up time	After approx. 5 minutes the instrument will function to the specifications (accuracy)

Input	Measuring deviation per DIN EN 60770, 23 °C ±3 K	Mean temperature coefficient (TC) for each 10 K change in ambient temperature in the range -40 ... +85 °C	Lead resistance effects	Long-term stability after 1 year
■ Resistance thermometer Pt100/JPt100/ Ni100 [1]	-200 °C ≤ MV ≤ 200 °C: ±0.10 K MV > 200 °C: ±(0.1 K + 0.01 % |MW-200 K|) [2]	±(0.06 K + 0.015 % MV)	4-wire: no effect (0 to 50 Ω each wire) 3-wire: ±0.02 Ω / 10 Ω (0 to 50 Ω each wire) 2-wire: Resistor of the connection lead [3]	±60 mΩ or 0.05 % of MV, greater value applies
■ Resistance sensor	≤ 890 Ω: 0.053 Ω [4] or 0.015 % MV [5] ≤ 2,140 Ω: 0.128 Ω [4] or 0.015 % MV [5] ≤ 4,390 Ω: 0.263 Ω [4] or 0.015 % MV [5] ≤ 8,380 Ω: 0.503 Ω [4] or 0.015 % MV [5]	±(0.01 Ω + 0.01 % MV)		
■ Potentiometer	R_{part}/R_{total} is max. ±0.5 %	±(0.1 % MV)		±20 µV or 0.05 % of MV, greater value applies
■ Thermocouples Type E, J	-150 °C < MV < 0 °C: ±(0.3 K + 0.2 % |MV|) MV > 0 °C: ±(0.3 K + 0.03 % MV)	Type E: MV > -150 °C: ±(0.1 K + 0.015 % |MV|) Type J: MV > -150 °C: ±(0.07 K + 0.02 % |MV|)	6 µV / 1,000 Ω [6]	
Type T, U	-150 °C < MV < 0 °C: ±(0.4 K + 0.2 % |MV|) MV > 0 °C: ±(0.4 K + 0.01 % MV)	-150 °C < MV < 0 °C: ±(0.07 K + 0.04 % MV) MV > 0 °C: ±(0.07 K + 0.01 % MV)		
Type R, S	50 °C < MV < 400 °C: ±(1.45 K + 0.12 % |MV - 400 K|) 400 °C < MV < 1,600 °C: ±(1.45 K + 0.01 % |MV - 400 K|)	Type R: 50 °C < MV < 1,600 °C: ±(0.3 K + 0.01 % |MV - 400 K|) Type S: 50 °C < MV < 1,600 °C: ±(0.3 K + 0.015 % |MV - 400 K|)		
Type B	450 °C < MV < 1,000 °C: ±(1.7 K + 0.2 % |MV - 1,000 K|) MV > 1,000 °C: ±1.7 K	450 °C < MV < 1,000 °C: ±(0.4 K + 0.02 % |MV - 1,000 K|) MV > 1,000 °C: ±(0.4 K + 0.005 % (MV - 1,000 K))		
Type K	-150 °C < MV < 0 °C: ±(0.4 K + 0.2 % |MV|) 0 °C < MV < 1,300 °C: ±(0.4 K + 0.04 % MV)	-150 °C < MV < 1,300 °C: ±(0.1 K + 0.02 % |MV|)		
Type L	-150 °C < MV < 0 °C: ±(0.3 K + 0.1 % |MV|) MV > 0 °C: ±(0.3 K + 0.03 % MV)	-150 °C < MV < 0 °C: ±(0.07 K + 0.02 % |MV|) MV > 0 °C: ±(0.07 K + 0.015 % MV)		
Type N	-150 °C < MV < 0 °C: ±(0.5 K + 0.2 % |MV|) MV > 0 °C: ±(0.5 K + 0.03 % MV)	-150 °C < MV < 0 °C: ±(0.1 K + 0.05 % |MV|) MV > 0 °C: ±(0.1 K + 0.02 % MV)		
■ mV sensor	≤1,160 mV: 10 µV + 0.03 % |MV| >1,160 mV: 15 µV + 0.07 % |MV|	2 µV + 0.02 % |MV| 100 µV + 0.08 % |MV|		
■ Cold junction [7]	±0.8 K	±0.1 K		±0.2 K
Output	±0.03 % of measuring span	±0.03 % of measuring span		±0.05 % of span

Total measuring deviation

Addition: Input + output per DIN EN 60770, 23 °C ± 3 K

MV = measured value (temperature measured values in °C)
Measuring span = configured end of measuring range - configured start of measuring range

1) For sensor Ptx (x = 10 ... 1,000) applies:
for x ≥ 100: Permissible error, as for Pt100
for x < 100: Permissible error, as for Pt100 with a factor (100/x)
2) Additional error for resistance thermometers in a 3-wire configuration with zero-balanced cable: 0.05 K
3) The specified resistance value of the sensor wire can be subtracted from the calculated sensor resistance.
Dual sensor: Configurable for each sensor separately
4) Double value at 3-wire
5) Greater value applies
6) Within a range of 0 ... 10 kΩ lead resistance
7) Only for thermocouple

Basic configuration:
Input signal: Pt100 in 3-wire connection, measuring range: 0 ... 150 °C

Example calculation

Pt100 / 4-wire / measuring range 0 ... 150 °C / ambient temperature 33 °C	
Input Pt100, MV < 200 °C	±0.100 K
Output ±(0.03 % of 150 K)	±0.045 K
TC 10 K - input ±(0.06 K + 0.015 % of 150 K)	±0.083 K
TC 10 K - output ±(0.03 % of 150 K)	±0.045 K
Measuring deviation (typical) $\sqrt{input^2 + output^2 + TC_{input}^2 + TC_{output}^2}$	**±0.145 K**
Measuring deviation (maximum) (input + output + TC_{input} + TC_{output})	**±0.273 K**

Thermocouple type K / measuring range 0 ... 400 °C / internal compensation (cold junction) / ambient temperature 23 °C	
Input type K, 0 °C < MV < 1,300 °C ±(0.4 K + 0.04 % of 400 K)	±0.56 K
Cold junction ±0.8 K	±0.80 K
Output ±(0.03 % of 400 K)	±0.12 K
Measuring deviation (typical) $\sqrt{input^2 + cold\ junction^2 + output^2}$	**±0.98 K**
Measuring deviation (maximum) (input + cold junction + output)	**±1.48 K**

Monitoring		
Test current for sensor monitoring [1]	Nom. 20 µA during test cycle, otherwise 0 µA	
Monitoring NAMUR NE89 (monitoring of input lead resistance)		
■ Resistance thermometer (Pt100, 4-wire)	$R_{L1} + R_{L4} > 100\ \Omega$ with hysteresis 5 Ω $R_{L2} + R_{L3} > 100\ \Omega$ with hysteresis 5 Ω	
■ Thermocouple	$R_{L1} + R_{L4} + R_{thermocouple} > 10\ k\Omega$ with hysteresis 100 Ω	
Sensor break monitoring	Always active	
Self-monitoring	Active permanently, e.g. RAM/ROM test, logical program operating checks and validity check	
Measuring range monitoring	Monitoring of the set measuring range for upper/lower deviations Standard: Deactivated	
Monitoring of input lead resistance (3-wire)	Monitoring of the resistance difference between lead 3 and 4; an error will be indicated if there is a difference of > 0.5 Ω between leads 3 and 4	

1) Only for thermocouple

Field case		
Material	■ Aluminium, window from polycarbonate ■ Stainless steel, window from polycarbonate	
Colour	Aluminium: Night blue, RAL 5022	Stainless steel: Silver
Cable bushings	3 x M20 x 1.5 or 3 x ½ NPT	
Ingress protection	IP66	
Weight	Aluminium: approx. 1.5 kg	Stainless steel: approx. 3.7 kg
Dimensions	See drawing	

Ambient conditions	
Ambient temperature	-60 [1] / -40 ... +85 °C
Functional area of the display	-20 [2] ... +70 °C
Climate class per IEC 654-1: 1993	Cx (-20 ... +85 °C, 35 ... 85 % r. h., non-condensing)
Maximum permissible humidity	93 % r. h. ±3 %
Vibration resistance per IEC 60068-2-6:2007	3 g
Shock resistance per IEC 68-2-27: 1987	30 g
Electromagnetic compatibility (EMC)	EN 61326 emission (group 1, class B) and interference immunity (industrial application), and also NAMUR NE21

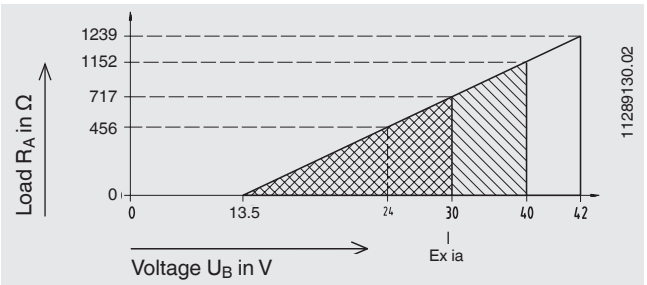
1) Special version on request (only available with specific approvals)
2) In previous ambient temperatures < -20 °C a delayed recovery of the indication function could be expected, especially in case of low loop current.

Communication HART® protocol rev. 5 including burst mode and multidrop
Interoperability (i.e. compatibility between components from different manufacturers) is a strict requirement of HART® instruments. The field transmitter is compatible with almost every open software and hardware tool; among other things with:
1. User-friendly WIKA configuration software, free-of-charge download via www.wika.com
2. HART® communicator FC375, FC475, MFC4150, MFC5150, Trex:
   T32 device description integrated
3. Asset Management Systems
   3.1 AMS: T32_DD completely integrated and upgradable with old versions
   3.2 Simatic PDM: T32_EDD completely integrated from version 5.1, upgradable with version 5.0.2
   3.3 Smart Vision: DTM upgradable per FDT standard from SV version 4
   3.4 PACTware: DTM completely integrated and upgradable as well as all supporting applications with FDT interface
   3.5 Field Mate: DTM upgradable

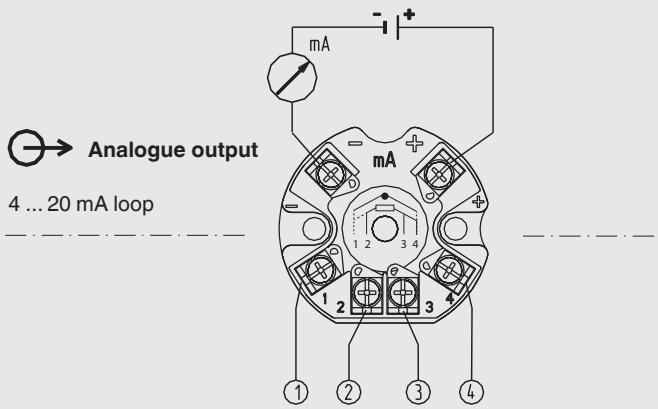
Attention:
For direct communication via the serial interface of a PC/notebook, a HART® modem is needed (see “Accessories”).
As a general rule, parameters which are defined in the scope of the universal HART® commands (e.g. the measuring range) can, in principle, be edited with all HART® configuration tools.

Load diagram
The permissible load depends on the loop supply voltage.

Load $R_A \leq (UB - 13.5\ V) / 0.023\ A$ with R_A in Ω and U_B in V (without HART®)



Designation of connection terminals



Identical dual sensors are supported for all sensor types, i. e. dual sensor combinations as for example Pt100/Pt100 or thermocouple type K/type K are possible.
A further rule is that both sensor values have the same unit and the same sensor range.

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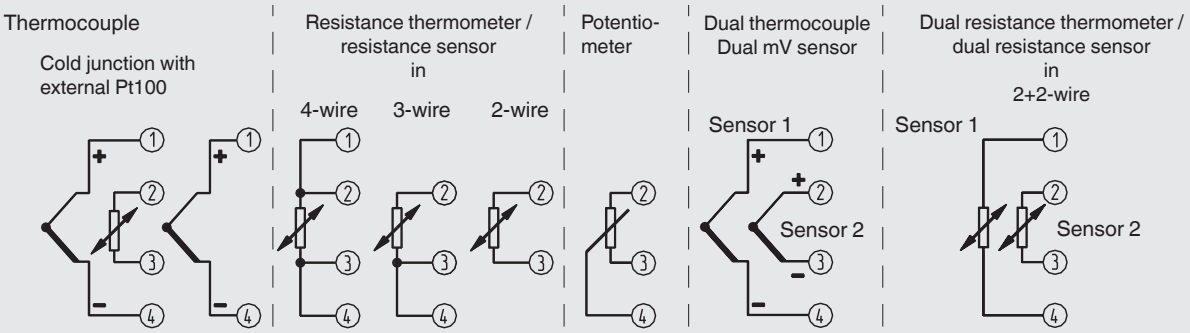
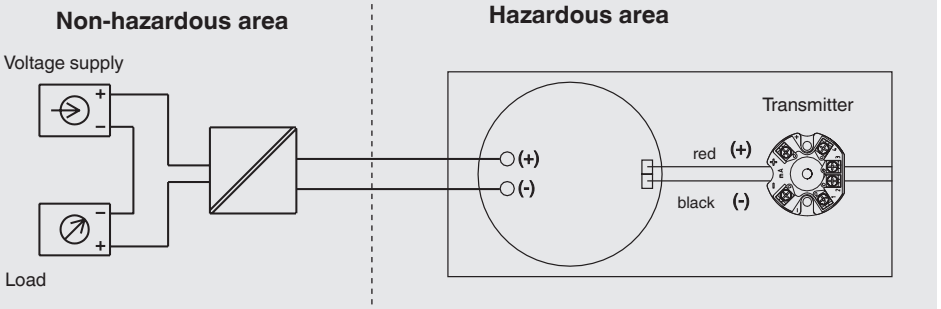
Input resistance sensor / thermocouple



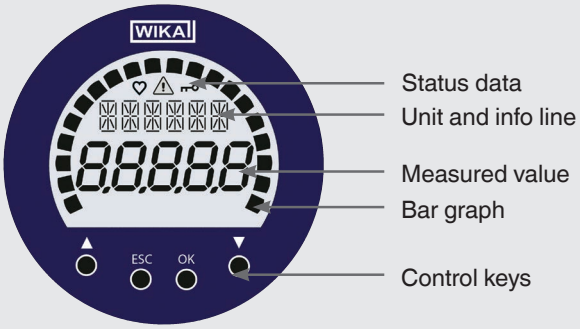
For the HART® modem, connection terminals are available for the head-mounted case and additional terminals are available for the rail-mounted case.

Electrical connection



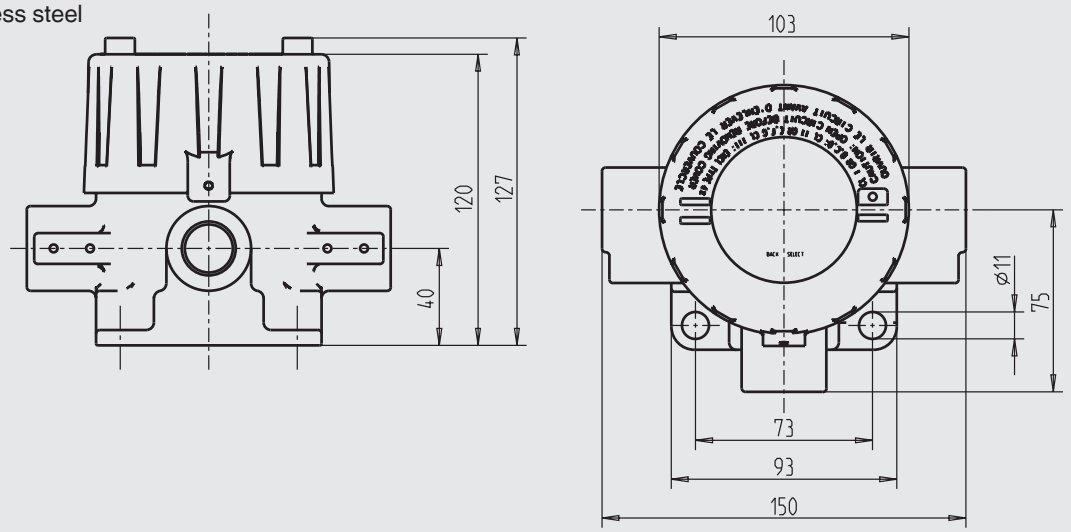
Legend:
Voltage supply
Load
(-) Supply minus
(+) Supply plus
2-wire connection

User interface



Dimensions in mm

Aluminium
Stainless steel



Accessories

Model	Description	Order number
Programming unit, model PU-H		
VIATOR® HART® USB 	HART® modem for USB interface	11025166
VIATOR® HART® USB PowerXpress™ 	HART® modem for USB interface	14133234
VIATOR® HART® RS-232 	HART® modem for RS-232 interface	7957522
VIATOR® HART® Bluetooth® Ex 	HART® modem for Bluetooth interface, Ex	11364254
Magnetic quick connector magWIK 	■ Replacement for crocodile clips and HART® terminals ■ Fast, safe and tight electrical connection ■ For all configuration and calibration processes	14026893

Approvals

Logo	Description	Region
CE	**EU declaration of conformity**	European Union
	EMC directive EN 61326 emission (group 1, class B) and interference immunity (industrial application)	
	RoHS directive	

Optional approvals

Logo	Description	Region
Ex	**EU declaration of conformity**	European Union
	ATEX directive Hazardous areas	
IEC IECEx	**IECEx** Hazardous areas	International
EAC Ex	**EAC**	Eurasian Economic Community
	EMC directive	
	Hazardous areas [1]	
	PAC Russia Metrology, measurement technology	Russia
	PAC Kazakhstan Metrology, measurement technology	Kazakhstan
-	**MChS** Permission for commissioning	Kazakhstan
	PAC Belarus Metrology, measurement technology	Belarus
	PAC Ukraine Metrology, measurement technology	Ukraine
	DNOP - MakNII	Ukraine
	Mining	
	Hazardous areas	
-	**PESO** Hazardous areas	India

1) The installation conditions for the transmitters must be considered for the final application.

Manufacturer‘s information and certifications

Logo	Description
-	**China RoHS directive**

Certificates (option)

Certificates	
Certificates	■ 2.2 test report ■ 3.1 inspection certificate
Calibration	■ DAkkS calibration certificate

→ Approvals and certificates, see website

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